

Today

Outline

Hardness of Approximation

Simulation Techniques

- Simulation

- Simplify Computation

- Structural Approximation

Simulation

Techniques

- Gibbs Sampling (MCMC)

- Forward Sampling

 - Logic Sampling

 - Likelihood Weighting

 - Bounded Variance

 - AA

- Backward Sampling

- Metropolis (MCMC)

Numeric Integration

- Gibbs+Metropolis: Samples drawn from Markov Chain

- Forward+Backward: Independent samples

Approximate Marginal

Techniques:

- Bounded Conditioning (Horvitz)

- Single Fault Approximation

- Adaptive Hugin (Kjaerwulf)

- Search (Henrion, Poole)

- Approximate Mixtures

 - Poland, West, Bar-Shalom, many others
(later in course)

Drop or combine terms

- Drop small probability terms.

- Combine similar terms.

Simplify Distribution

Assume Extra Independence

- Variational Approximation (Jordan) (May do this)

- LPE (Draper)

- Approximate Factoring (Boyer + Koller)

Solve a problem you know that you can solve.

Measuring Performance

Absolute Error

$$P\{X = x | E = e\} - \varepsilon \leq \rho \leq P\{X = x | E = e\} + \varepsilon$$

Relative Error

$$P\{X = x | E = e\}(1 - \varepsilon) \leq \rho \leq P\{X = x | E = e\}(1 + \varepsilon)$$

Epsilon-Delta Bound

$$P\{\varepsilon \text{ relative approximation to } P\{X | E\}\} \geq 1 - \delta$$

Hardness Results: Relative Error

(Koller) The problem of finding ρ with a relative error ε to $P\{X=x\}$ in a BN is NP-hard

Proof:

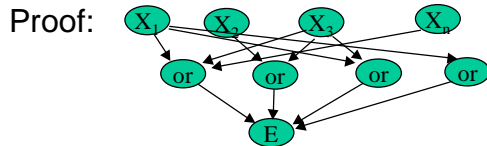
PIBNETB: $P\{\text{'AND'}\} > 0$

Use a "relative error" algorithm to estimate ρ to relative error ε

$\rho > 0$ iff $P\{\text{'AND'}\} > 0$

Hardness Results: Absolute Error

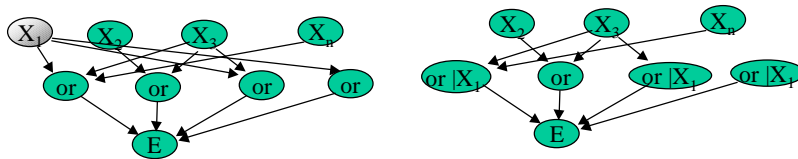
(Koller) The problem of finding an approximation ρ with absolute error $\varepsilon < 1/2$ to $P\{X=x|E=e\}$ is NP-hard



Estimate $P\{X_1|E=T\}$

If $\rho > 0$ Pick $X_1 = T$ [we know that $P\{X_1 = T|E = T\} > 0$]
 o/w Pick $X_1 = F$

Absolute Error Proof Continued



Estimate $P\{X_2|E=T\}, \dots, P\{X_n|E=T\}$
 choosing X_i that maximizes $\rho\{X_i|E=T\}$,
 $P\{X\} > 0$

Hardness: Absolute Epsilon-Delta

(Dagum+Luby)

The problem of finding ρ such that

$$P\left\{P\{X = x | E = e\} - \frac{1}{2} < \rho < P\{X = x | E = e\} + \frac{1}{2}\right\} > \frac{1}{2}$$

is NP-hard

Simulation

Forward Sampling

Logic Sampling

Likelihood Weighting

Bounded Variance

AA

Backward Sampling

Gibbs Sampling (MCMC)

Metropolis (MCMC)

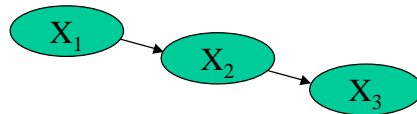
Why Simulation?

Can solve problems that don't have closed-form solutions

For prediction problems, estimate accuracy increases

as $\frac{1}{\sqrt{n}}$

Forward Sampling

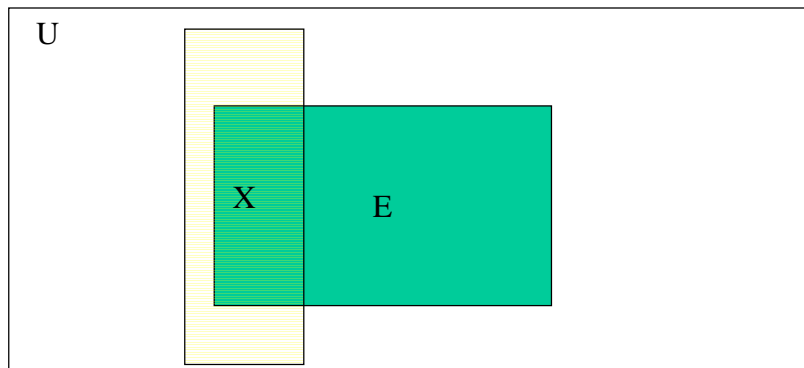


Sample from $P\{X\}$:

1. Sample x_1 from $P\{X_1\}$
2. Sample x_2 from $P\{X_2|X_1=x_1\}$
3. Sample x_3 from $P\{X_3|X_1=x_1, X_2=x_2\}$

Rejection Sampling

Estimate $P(X|E)$



Logic or Rejection Sampling (Henrion 87)

Goal: Estimate $P\{Q=f(X)|E=e\}$

Let X = unobserved, E = observed
and $Z = X \cup E$

Using Forward Sampling, collect N samples $Z[1], \dots, Z[N]$

$$P(e) \approx \frac{1}{N} \sum_i I(E = e | Z[i]) \quad P(e) \approx \frac{1}{N} \sum_i I(Q = q, E = e | Z[i])$$

$$P(q|e) \approx \frac{\sum_i I(Q = q, E = e | Z[i])}{\sum_i I(E = e | Z[i])}$$

Likelihood Weighting (Shachter+Peot, Fung+Chang)

Goal: Estimate $P\{Q=f(X)|E=e\}$

Let X = unobserved, E = observed

Path Prior:
$$\rho(X) = \prod_X P\{X_i | pa(X_i)\}$$

Path Likelihood:
$$\omega(E) = \lambda(E) = \prod_E P\{E_i | pa(E_i)\}$$

Likelihood Weighting, continued

Forward-sample X from the path prior: $X[1], \dots, X[N]$

Score:
$$P(e) \approx \frac{1}{N} \sum_i \omega(X[i])$$

$$P(Q = q, e) \approx \frac{1}{N} \sum_i I(q | X[i]) \omega(X[i])$$

$$P(Q = q | e) \approx \frac{\sum_i I(q | X[i]) \omega(X[i])}{\sum_i \omega(X[i])}$$

Likelihood Weighting, cont'd

As $N \rightarrow$ infinity

$$\begin{aligned}\sum_i I(q | X[i]) \omega(X[i]) &= \int I(q | X) \rho(X) \omega(X) dX \\ &= \int I(q | X) \prod_i P\{X_i | pa(X_i)\} dX \\ &= \int I(q | X) P\{X, E\} dX \\ &= P\{q, E\}\end{aligned}$$

Importance Sampling

Sample from $\rho'(X)$

Score:
$$\omega(X) = \frac{\rho(X)}{\rho'(X)} \lambda(X)$$

$$\begin{aligned}\sum_i I(q | X[i]) \omega(X[i]) &= \int I(q | X) \rho'(X) \frac{\rho(X)}{\rho'(X)} \lambda(X) dX \\ &= \int I(q | X) \rho(X) \lambda(X) dX \\ &= P\{q, E\}\end{aligned}$$

Likelihood Weighting, Convergence

Say that $P(Q=q)$ has mean μ and variance σ^2 .

Chebychev:

$$P\left\{\left|\frac{\hat{\mu} - \mu}{\mu}\right| > \varepsilon\right\} < \frac{c\sigma^2}{N\varepsilon^2\mu^2} \leq \delta$$

$$N \geq \frac{c\sigma^2}{\varepsilon^2\mu^2} \cdot \frac{1}{\delta}$$

Generalized $\{0,1\}$ Estimator Theorem

(Dagum, Karp, Luby, Ross)

let Z_1, \dots, Z_N denote i.i.d. random variables, distributed according to Z . If $\varepsilon < 1$, and

$$N = \Psi \cdot \frac{k_Z}{(\mu_Z)^2} \quad \Psi = 4(e-2) \ln\left(\frac{2}{\delta}\right) \frac{1}{\varepsilon^2}$$

$$k_Z = \max\{\sigma_Z^2, \varepsilon\mu_Z\}$$

then

$$P\left[(1-\varepsilon)\mu_Z \leq \sum_{i=1}^N \frac{Z_i}{N} \leq (1+\varepsilon)\mu_Z\right] > 1-\delta$$

Likelihood Weighting, better bound

$$N = 4(e-2) \ln\left(\frac{2}{\delta}\right) \frac{1}{\varepsilon^2} \cdot \frac{\max\{\sigma^2, \varepsilon\mu\}}{(\mu)^2}$$

$$N = 4(e-2) \ln\left(\frac{2}{\delta}\right) \frac{1}{\varepsilon^2} \cdot \frac{(1-\mu)}{\mu} \qquad N = 4(e-2) \ln\left(\frac{2}{\delta}\right) \frac{1}{\mu\varepsilon}$$

LVB

Localized variance bound for estimating any joint probability.

Let $u(X_i)$ denote the maximum of $P\{X_i = x_i\}$

and $l(X_i)$ denote the minimum.

$$\Gamma_i = \max\left\{\frac{u(X_i)}{l(X_i)}, \frac{1-l(X_i)}{1-u(X_i)}\right\}$$

$$\Gamma = \prod_i \Gamma_i$$

$$N = 4(e-2) \ln\left(\frac{2}{\delta}\right) \frac{1}{\varepsilon^2} \cdot \frac{1}{\mu} = 4(e-2) \ln\left(\frac{2}{\delta}\right) \frac{1}{\varepsilon^2} \cdot \Gamma$$

Bounded Variance (Dagum+Luby)

Estimate $P(x)$

1. LW rejects samples because of $I(x|X)$
2. No good prior bound on μ and σ^2

Solution

Estimate μ on the fly.

Stopping rule based on cumulative sum.

Gibbs Sampling

For each observed variable E_i , set $E_i = e_i$.

Use any sampling technique (usually forward-sampling or importance-sampling) to set X_i to some random value.

Repeat

Pick some unobserved variable X_i

Sample $X_{i[j]} \sim P\{X_i | X_1, \dots, X_{i-1}, X_{i+1}, \dots, X_n\}$

Question, what is $P\{X_i | X_1, \dots, X_{i-1}, X_{i+1}, \dots, X_n\}$?

Procedures

Parallel:

“Burn-in” by Gibbs for some period of time. Sample.
Sample is in $P\{X|E\}$

Serial:

If $x[i]$ is from $P(X|E)$, then, so is $x[i+1]$.

Say that x_1 is flipped:

$$\begin{aligned} P\{X[i+1]\} &= \sum_{x_1} P\{x'_1 | x_2, \dots, x_n\} P\{x_1, x_2, \dots, x_n\} \\ &= \sum_{x_1} P\{x'_1 | x_2, \dots, x_n\} P\{x_1 | x_2, \dots, x_n\} P\{x_2, \dots, x_n\} \\ &= P\{x'_1 | x_2, \dots, x_n\} P\{x_2, \dots, x_n\} \sum_{x_i} P\{x_1 | x_2, \dots, x_n\} \\ &= P\{x'_1, x_2, \dots, x_n\} \end{aligned}$$

Pluses/Minuses

Brooks (98):

- (-) No good convergence result known for Gibbs
- (+) Includes evidence in sampling.